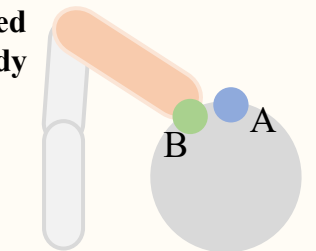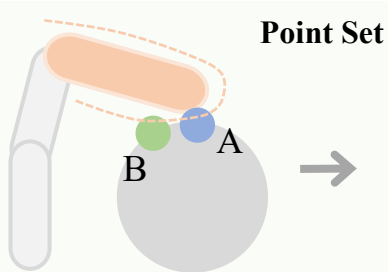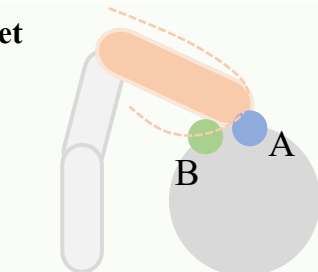**Articulated Multi-Body**

Wish to change the contact point from A to B

Result: adjust **two** joint states to achieve this

Point Set

Wish to change the contact point from A to B

Result: adjust **one** joint state and a few point states

Noise in data

Transfer w/o Point set

Transfer w/ Point set